



DÜSTERLOH **Fluidtechnik**

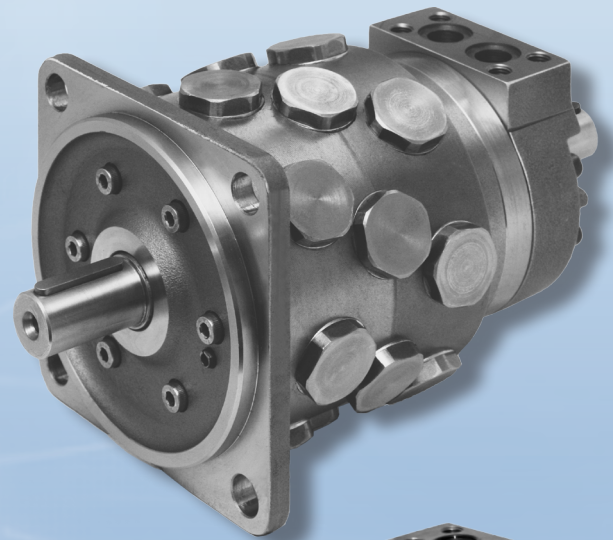
High-Precision Hydraulic Motors

Radial Piston Motors

with fixed displacement

RMHP 90 - RMHP 110

$V_g = 88,4 \text{ ccm/rev} - 109,5 \text{ ccm/rev}$

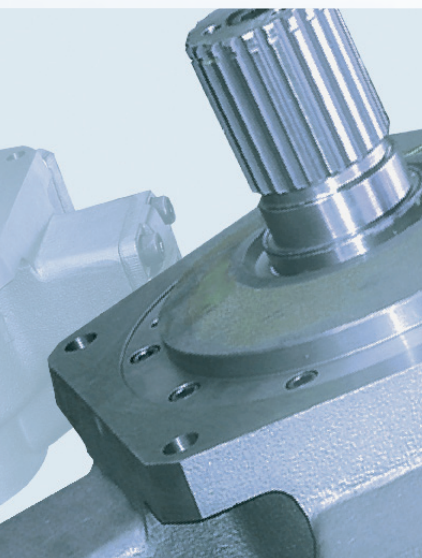
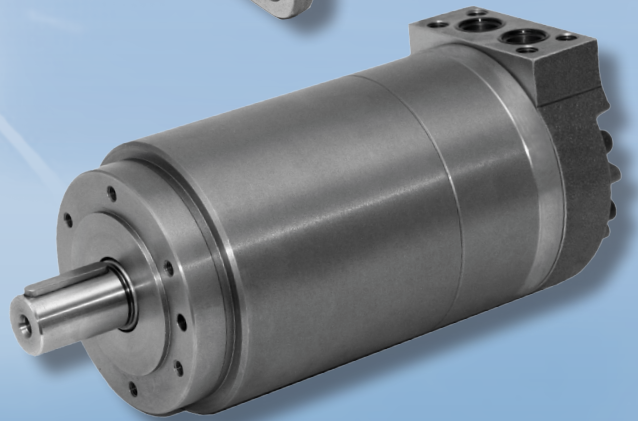


Axial Piston Motor

with fixed displacement

AEHP 40

$V_g = 43,7 \text{ ccm/rev}$



Doc.-No. HM1-018 UK

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Special characteristics of the high precision hydraulic motors

Düsterloh high precision hydraulic motors generate an extreme low cyclic irregularity. The RMHP-motors have a cyclic irregularity of just 0,28 % and the AEHP of 0,73 %. In combination with a highly precise control of the oil flow to the pistons, the motors generate a high speed constancy, specially by driving low numbers of rotations.

Characteristics of the high precision Düsterloh hydraulic motors

- long service due to mature design
- shaft end able to support large radial and axial forces
- small number of components in drive
- extreme low moment of inertia
- by default with measuring shaft
- translationally operating control unit with play adjustment control
- suitable for use with liquids with low combustion properties
- maintenance free
- quiet running
- wide speed range
- 100 % torque throughout the entire speed range
- immediately reversible
- high starting torque
- no counterpressure required for motor operation
- can be used as pump if feed is available
- suitable for several applications as a control unit
- feed and discharge control possible
- total efficiency of up to 93 %
- direct valve mounting available as a standard option

Characteristic:

Motor	Displacement V_g [ccm/rev]	Torque		Speed		Cont. pressure $p_{cont.}$ [bar]	Maximum pressure p_{max} [bar]	Peak pressure p_{peak} [bar]	Output	
		T_{spec} [Nm/bar]	T_{max} [Nm]	n_{min*} [rpm]	n_{max} [rpm]				$P_{cont.}$ [kW]	$P_{intermit.}$ [kW]
RMHP 90	88,4	1,24	252	1	900	140	210	250	8,5	10
RMHP 110	109,5	1,55	310	1	750	140	210	250	8,5	10
AEHP 40	43,7	0,63	155	1	2000	210	250	315	18,0	21

Calculation - Performance limits:

With known pressure difference Δp :

$$RMHP\ 90: \quad n \leq \frac{8,5kW \times 9549,3}{\Delta p \times 1,24Nm/bar} = \frac{65459}{\Delta p} \quad [rpm]$$

$$RMHP\ 110: \quad n \leq \frac{8,5kW \times 9549,3}{\Delta p \times 1,55Nm/bar} = \frac{52367}{\Delta p} \quad [rpm]$$

$$AEHP\ 40: \quad n \leq \frac{18kW \times 9549,3}{\Delta p \times 0,63Nm/bar} = \frac{272837}{\Delta p} \quad [rpm]$$

With known number of rotations n :

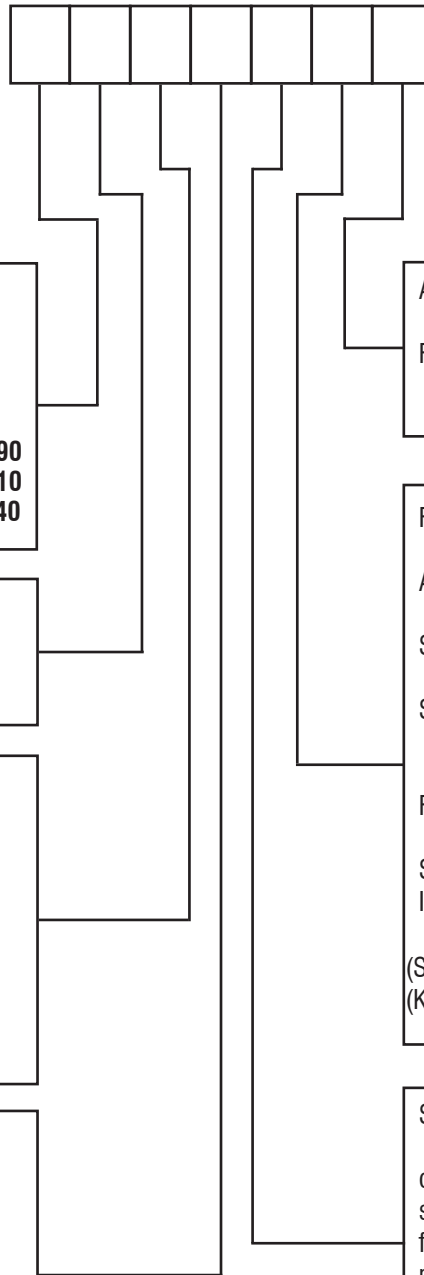
$$\Delta p \leq \frac{8,5kW \times 9549,3}{n \times 1,24Nm/bar} = \frac{65459}{n} \quad [bar]$$

$$\Delta p \leq \frac{8,5kW \times 9549,3}{n \times 1,55Nm/bar} = \frac{52367}{n} \quad [bar]$$

$$\Delta p \leq \frac{18kW \times 9549,3}{n \times 0,63Nm/bar} = \frac{272837}{n} \quad [bar]$$

Δp inlet pressure p_1 minus outlet pressure p_2
 $p_{cont.}$ if limited to $P_{cont.}$
 p_{max} if limited to $P_{intermit.}$ operating for a maximum duration of 10 % in every hour
 p_{peak} highest pressure at which the components will remain functional
 $P_{cont.}$ continuous output (at a return pressure of 10 bar); if this output is constantly exceeded, the drive must be flushed
 $P_{intermit.}$ output with which the motor can be run intermittently (for an operating time of 10 % in every hour).

High-precision hydro motor



Motortyp
with play self-adjustment

Motortyp/Displacement	Denotation
Radial-piston motor 88 cm ³ /U	= RMHP 90
Radial-piston motor 109 cm ³ /U	= RMHP 110
Axial-piston motor 44 cm ³ /U	= AEHP 40

Drive shaft	Denotation
Cylindrical Keyway DIN 6885 T1	= Z

Connections	Denotation
Flange connection, radial Duesterloh standard (for mounting the valve)	= A1
Threaded connection, radial G 1/2 DIN ISO 228-1	= A
Threaded connection, axial G 3/4 DIN ISO 228-1	= B5

Sealing material	Denotation
NBR seals, suitable for HLP mineral oils according to DIN 51524 part 2	= *
FPM seals, suitable for ester of phosphoric acid (HFD).	= V

Additional information	Denotation
Flush connection	= S99 (AEHP standard)

Flange dimensions	Denotation
Attachment	
S = ø80; K = ø100	= *
S = ø120; K = ø140	= F3 (only RMHP)
Flange connection	
S = ø160; K = ø200	= F ISO 3019/2
(S = diameter of the centring ring) (K = circle diameter for screw holes)	

Second shaft end	Denotation
cylindrical measuring shaft ø10 _{h6} for sensor (incre- mental speed sensor etc.)	= M (Not available for B5 connections)
without second shaft end	= *

* No information given in the type key number.

1. General properties and features

Hydrostatic radial piston motor

Purpose:

Transformation of hydraulic power to drive power.

High efficiency, also suitable for very low speeds, low moment of inertia, rapidly reversible, four-quadrant operation possible, very suitable for applications as a control, quiet operation.

2. Structure and function

2.1 Drive unit

Design:

Internal piston support

Method of functioning:

Twenty-one radial pistons (1) load the crankshaft (4) via a heptagon ring (2) with a needle bearing (3).

Drive details

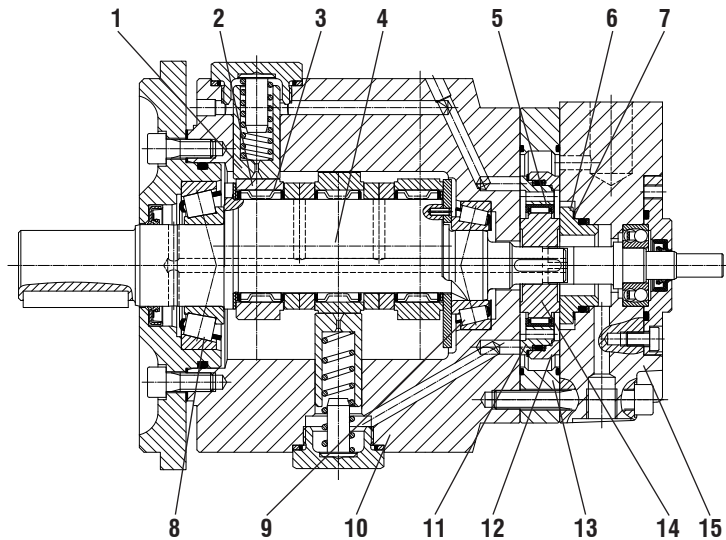
Crankshaft bearing: Prestressed, amply dimensioned taper roller bearing (8/9) in X-arrangement.

High guiding accuracy, therefore smooth running, high axial and radial load capacity (e.g. a flying arrangement of a pinion on the drive shaft). Load transmission piston (1) - crank shaft (4):

Through heptagon ring (2) with needle bearing (3).

Advantage: Low frictional losses, very long service life,

relatively insensitive to dirt, high starting torque, high continuous torque, no stick-slip effect at low speeds, only minor leakage (necessary for the lubrication and cooling of the drive), high efficiency.



2.2 Control

Design:

Planar translational distribution valve with play adjustment.

Purpose:

Distribution of the volume feed to the twenty-one cylinders, collection of the return volume flow.

Method of functioning:

Control rings (11/12) with the external ring (13) and with the eccentric (14) form an external and an internal ring space.

By moving the control rings (11/12) between the motor housing (10) and the end cover (15) by means of the eccentric (14) which is fixed to the crankshaft (14), the internal and the external ring spaces are connected to the cylinders in turn. The ring spaces themselves are connected to the outside through pressure connections to the motor.

Control details

Roller bearing (5) between the control rings (11/12) and the eccentric (14). The control rings (11/12) mainly move translationally, nevertheless rotational movement is possible (two-degree-of-freedom-system) - this means small frictional losses at the control rings (11/12) and a cleaning effect in the sealing gap, approximately equal relative speeds of the sealing faces. Sinusoidal opening function for the control openings - this means smooth running even at low speeds and quiet running at high speeds, large volume flow in the control ring (11).

Adjustment of the play on the control rings (11/12) and the flats on the eccentric (14):

Through hydrostatic pressure, the control rings (11/12) are forced against the flats. In case of zero and low pressure situations, the contact between rings and flats is guaranteed throughout a spring washer, hydrostatic re-adjustment of the eccentric flats to each other, supported by a pressure thrust piece (6) and by a helical spring (7).

Very low leakage and small frictional losses, automatic compensation of pressure and temperature influences (temperature shocks among others), relatively insensitive to dirt.

1. General properties and features

Hydrostatic axial piston motor

Purpose:

Transformation of hydraulic power to drive power. High efficiency, also suitable for very low speeds, low moment of inertia, rapidly reversible, high totals printout load capacity, four-quadrant operation possible, very suitable for applications as a control, quiet operation.

2. Structure and function

2.1 Drive unit

Design:

Wobble plate

Method of functioning:

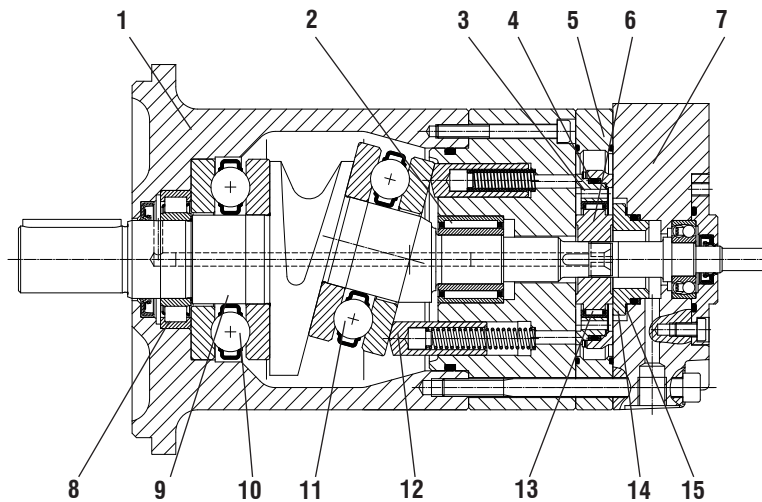
Thirteen axial pistons (12) load the wobble spindle (9) via deep groove ball thrust bearing (11).

Drive details

Balanced wobble spindle (9), bedded in a deep groove ball thrust bearing (10) and a cylinder roller bearing (8) facing drive side. The wobble spindle (9) facing the control unit is bedded in a needle bearing (2). High radial load capacity (e.g. a flying arrangement of a pinion on the drive shaft). The generation

of the torque results from the power transmission through the operating medium to the pistons (12). By means of deep groove ball thrust bearings (10/11) in combination with the wobble plate the pistons affect the wobble spindle (9).

Advantage: Low frictional losses, very long service life, relatively insensitive to dirt, high starting torque, high continuous torque, no stick-slip effect at low speeds, only minor leakage (necessary for the lubrication and cooling of the drive), high efficiency.



2.2 Control

Design:

Planar translational distribution valve with play adjustment.

Purpose:

Distribution of the volume flow to the thirteen cylinders, collection of the return volume flow.

Method of functioning:

Control rings (3/4) with the external ring (5) and with the eccentric (6) form an external and an internal ring space.

By moving the control rings (3/4) between the motor housing (1) and the end cover (7) by means of the eccentric (6) which is fixed to the wobble spindle (9), the internal and the external ring spaces are connected to the cylinders in turn. The ring spaces themselves are connected to the outside through pressure connections to the motor.

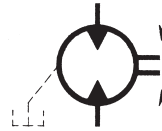
Control details

Roller bearing (13) between the control rings (3/4) and the eccentric (6). The control rings (3/4) mainly move translationally, nevertheless rotational movement is possible (two-degree-of-freedom-system) - this means small frictional losses at the control rings (3/4) and a cleaning effect in the sealing gap, approximately identical relative speeds of the sealing faces. Sinusoidal opening function for the control openings - this means smooth running even at low speeds and quiet running at high speeds, large volume flow in the control ring (13).

Adjustment of the play on the control rings (3/4) and the flats on the eccentric (6):

Through hydrostatic pressure, the control rings (3/4) are forced against the flats. In case of zero and low pressure situations, the contact between rings and flats is guaranteed throughout a spring washer, hydrostatic re-adjustment of the eccentric flats to each other, supported by a pressure thrust piece (14) and by a helical spring (15).

Very low leakage and small frictional losses, automatic compensation of pressure and temperature influences (temperature shocks among others), relatively insensitive to dirt.



RMHP 90 ZA1MF

Hydraulic characteristic values RMHP 90

Geometr. displacement	[ccm/rev]	88,4
Theor.spec. torque	[Nm/bar]	1,4
Average spec. torque	[Nm/bar]	1,24
Peak pressure*	[bar]	250,0
Max. operating pressure**	[bar]	210,0
Continuous pressure	[bar]	140,0
Max. operating torque	[Nm]	252,0
Continuous torque	[Nm]	173,0
Drain line pressure:	[bar]	

Hydraulic fluid temperature range:	[K]	243- 363
	[°C]	-30-+90
Viscosity range	[mm ² /s]	20- 150
	(max. 1000 mm ² /s at start)	

Pressure fluids:

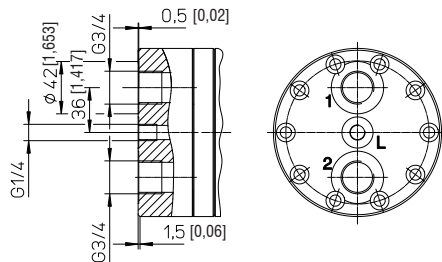
HM and HV, definition to CETOP RP 75 H (mineral oil based fluids).

Mineral oil H-LP in conformity with DIN 51424 part 2.

Bio-degradable fluids available on request.

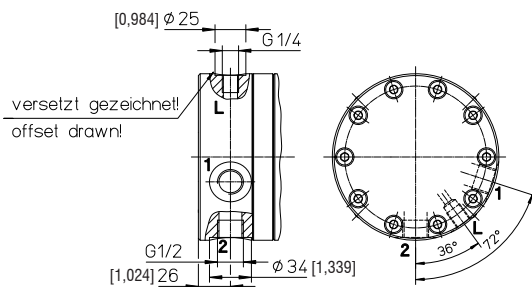
* Definition according to DIN 24 312. Peak pressure = exceeding the maximum operating pressure for a short time at which the motor remains able to function.

** If the sum of inlet pressure and outlet pressure is higher than the peak pressure, please consult the manufacturer.



Alternative End Cover B5

Inch measurements in brackets



Alternative End Cover A

Inch measurements in brackets

HFC	Reduce HFC pressure to 70 % Check the bearing service life	Definition to CETOP RP 77 H ISO/DIS 6071
HFD	FPM-/FKM seals are required	

Filtering

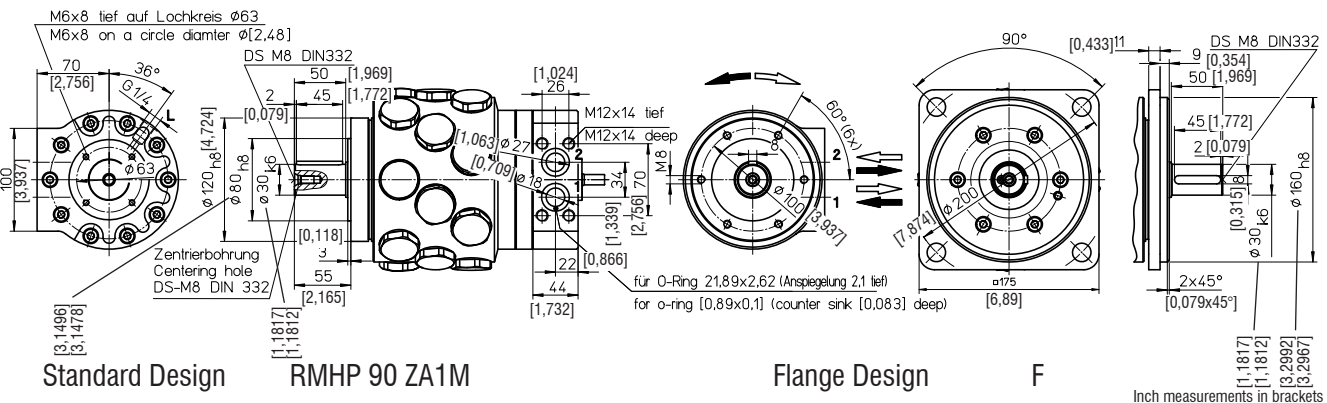
Max. permissible degree of contamination of the pressure fluid according to NAS 1638 class 9.

We recommend filters with a minimum retention rate of $\beta_{10} \geq 100$

For a long service life we recommend filtering acc. to NAS 1638 class 8 and filters with a minimum retention rate of $\beta_5 \geq 100$.

Characteristic values according to VDI 3278

Weight:	[kg]	25,2
Mounting position:	as required	
Direction of rotation, if viewed at the shaft end		
clockwise:	flow from connection 2 to connection 1	
anti-clockwise:	flow from connection 1 to connection 2	
Operating speed range:	[rpm]	1-900
Moment of inertia:	[kgm ²]	0,00032
Continuous power:	[kW]	8,5
Intermittent power:	[kW]	10,0



Standard Design RMHP 90 ZA1M

Flange Design F

Inch measurements in brackets

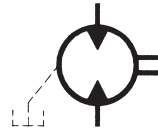
Type number key for radial piston motor RMHP 90

RMHP	Size 90	Shaft end Keyway Z	End cover Valve face A1 Radial ports A Axial ports B5	Seal NBR FPM V	Instrument shaft ¹⁾ with M without	Flange S=Ø 80;K=Ø100 S=Ø160;K=Ø200 S=Ø120;K=Ø140	additional specs. with out flush connection S99
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¹⁾ In Case of B5 flange, instrument shaft is not possible

Changes reserved!

DUESTERLOH Fluidtechnik GmbH · Im Vogelsang 105 · D-45527 Hattingen · Phone +49 / (0) 2324 / 709-0 · Fax +49 / (0) 2324 / 709-110



Pressure medium: HLP 46

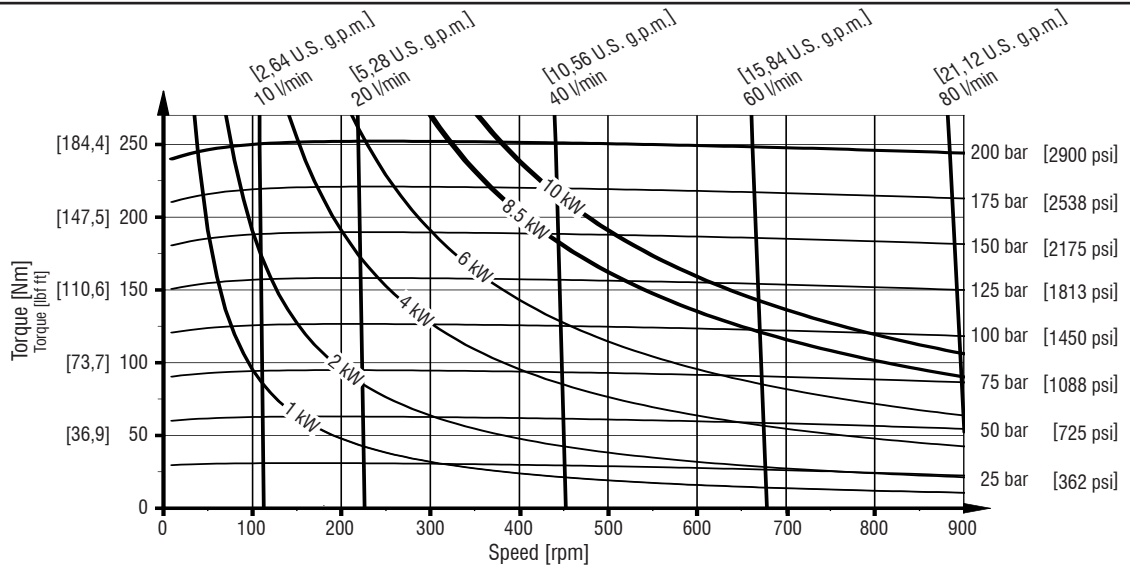
operating temperature: $T = 50^{\circ}\text{C}$

pressure difference: $\Delta p = p_1 - p_2$;

$p_2 = 0 \text{ bar}$

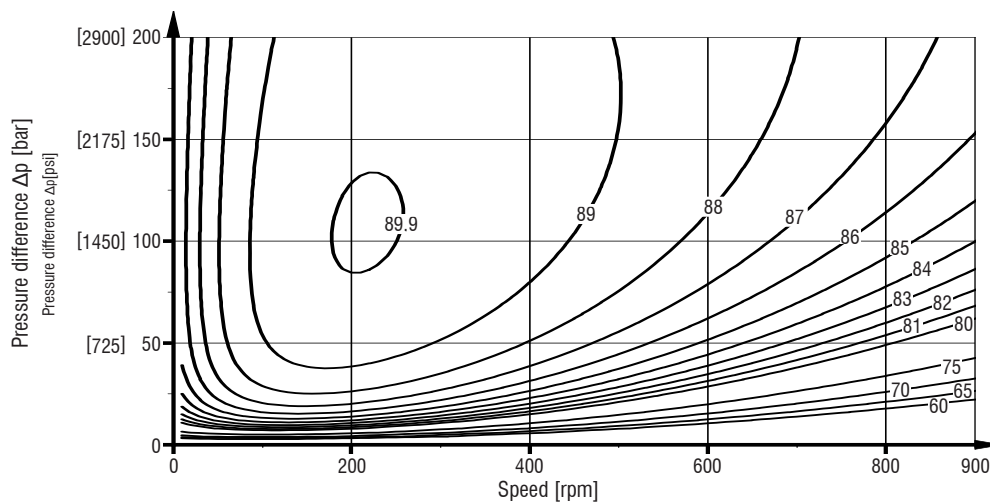
Torque characteristic

Diagram A:



Hydraulic-mechanical efficiency in percentage

Diagram B:



Strength of the shaft

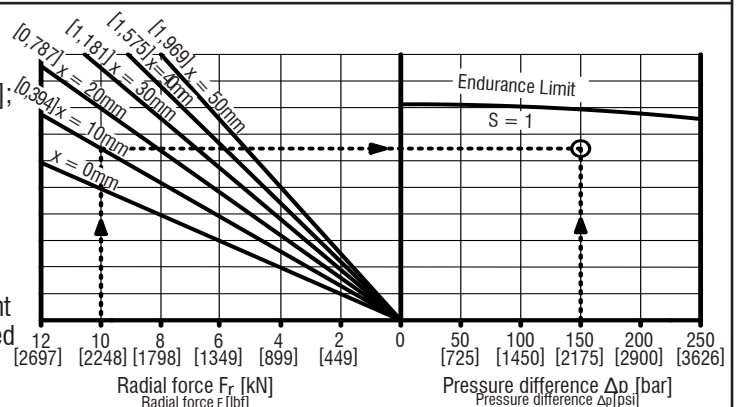
Diagram C:

Example:

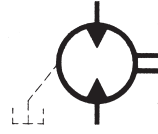
Given: $F_r = 10 \text{ kN}$ [2248 lbf]; $x = 10 \text{ mm}$ [0,394 in];
 $\Delta p = 150 \text{ bar}$ [2175,5 psi]

Required: Shaft strength

Draw a vertical line from $F_r = 10 \text{ kN}$ [2248 lbf] to distance $x = 10 \text{ mm}$ [0,394 in] and a straight horizontal line to the right. If the intersection of the horizontal with the vertical line of $\Delta p = 150 \text{ bar}$ [2175,5 psi] is below the curve, the shaft has sufficient fatigue strength. Allowable axial forces will be provided on request.



Changes reserved!



Pressure medium: HLP 46

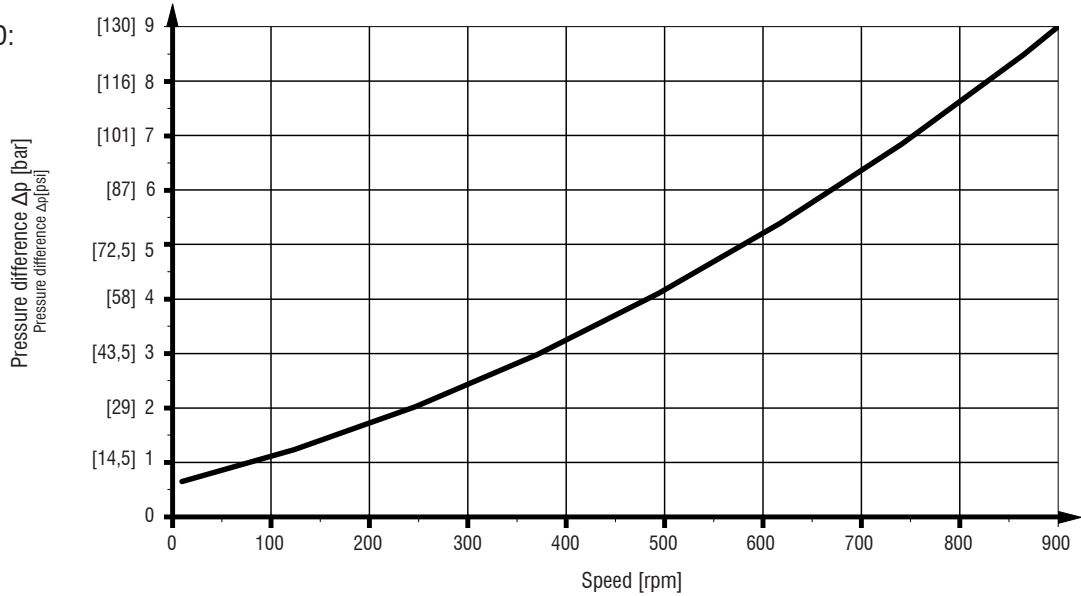
operating temperature: $T = 50^{\circ}\text{C}$

pressure difference: $\Delta p = p_1 - p_2$

$p_2 = 0 \text{ bar}$

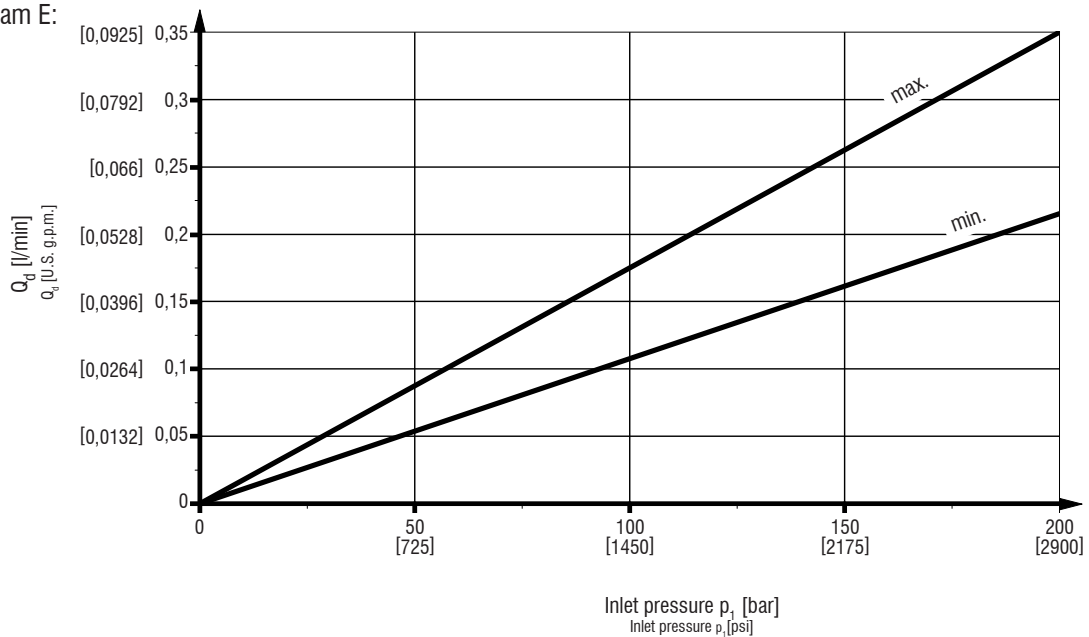
Idle speed

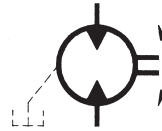
Diagram D:



External leakage through flow

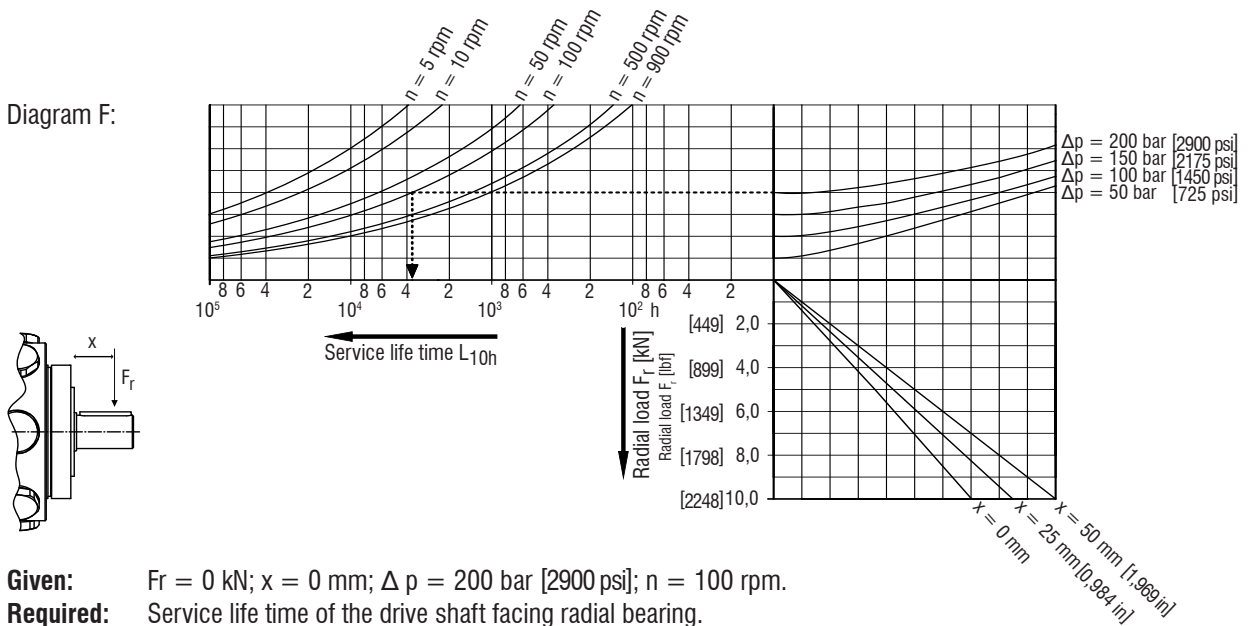
Diagram E:





Service life of the radial bearing loaded with a radial force facing the drive shaft.

Diagram F:

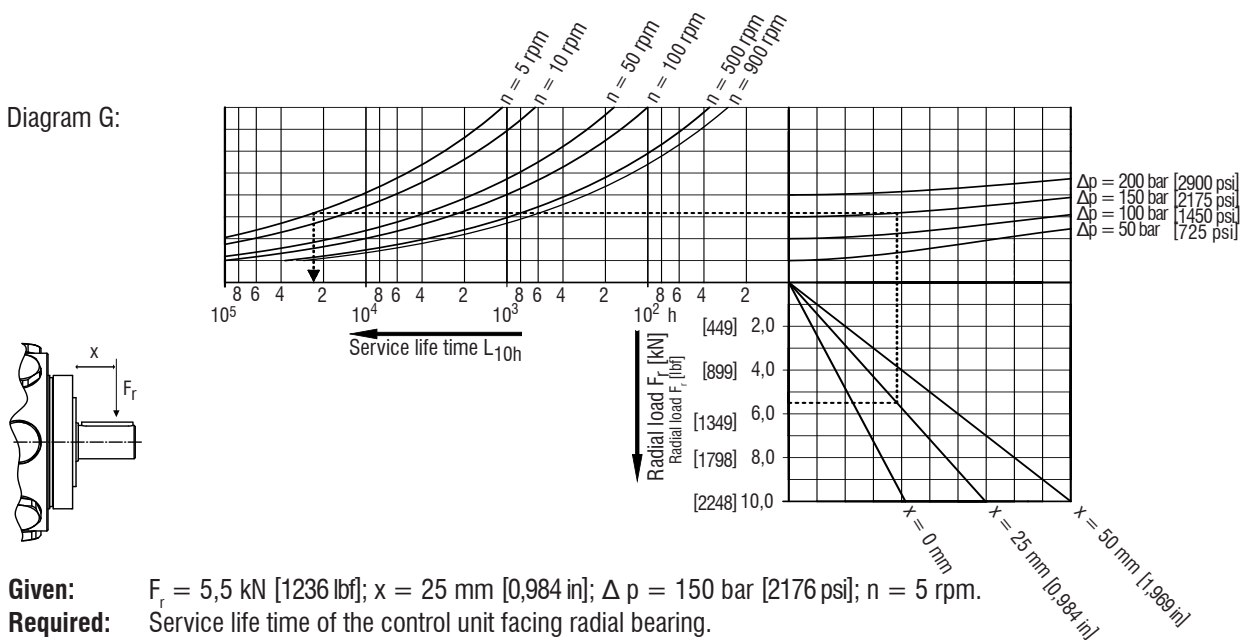


Given: $F_r = 0 \text{ kN}$; $x = 0 \text{ mm}$; $\Delta p = 200 \text{ bar}$ [2900 psi]; $n = 100 \text{ rpm}$.
Required: Service life time of the drive shaft facing radial bearing.

Diagram F:
Form a horizontal line from the $\Delta p = 200 \text{ bar}$ [2900 psi] curve to the $n = 100 \text{ rpm}$ curve. From this follows a service life time value of $L_{10h} = 3665,5 \text{ h}$.

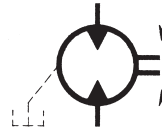
Service life of the radial bearing loaded with a radial force facing the control unit.

Diagram G:



Given: $F_r = 5,5 \text{ kN}$ [1236 lbf]; $x = 25 \text{ mm}$ [0,984 in]; $\Delta p = 150 \text{ bar}$ [2176 psi]; $n = 5 \text{ rpm}$.
Required: Service life time of the control unit facing radial bearing.

Diagram G:
Form a horizontal line from $F_r = 5,5 \text{ kN}$ [1236 lbf] to $x = 25 \text{ mm}$ [0,984 in]. From the intersection form a vertical line to the pressure curve $\Delta p = 150 \text{ bar}$ [2176 psi]. Afterwards, draw a line from the pressure curve to the speed curve $n = 5 \text{ rpm}$. The intersection shows the service life time $L_{10h} = 23351 \text{ h}$.



RMHP 110 ZA1MF

Hydraulic characteristic values RMHP 110

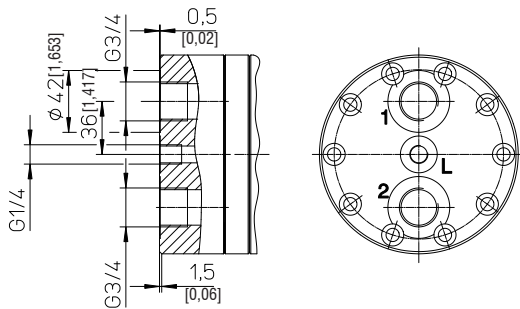
Geometr. displacement	[ccm/rev]	109,5
Theor.spec. torque	[Nm/bar]	1,74
Average spec. torque	[Nm/bar]	1,55
Peak pressure*	[bar]	250,0
Max. operating pressure**	[bar]	210,0
Continuous pressure	[bar]	140,0
Max. operating torque	[Nm]	310,0
Continuous torque	[Nm]	217,0
Drain line pressure:	[bar]	

Hydraulic fluid temperature range:	[K]	243- 363
	[°C]	-30- +90
Viscosity range	[mm ² /s]	20- 150
	(max. 1000 mm ² /s at start)	

Pressure fluids:
HM and HV, definition to CETOP RP 75 H (mineral oil based fluids).
Mineral oil H-LP in conformity with DIN 51424 part 2.
Bio-degradable fluids available on request.

* Definition according to DIN 24 312. Peak pressure = exceeding the maximum operating pressure for a short time at which the motor remains able to function.

** If the sum of inlet pressure and outlet pressure is higher than the peak pressure, please consult the manufacturer.



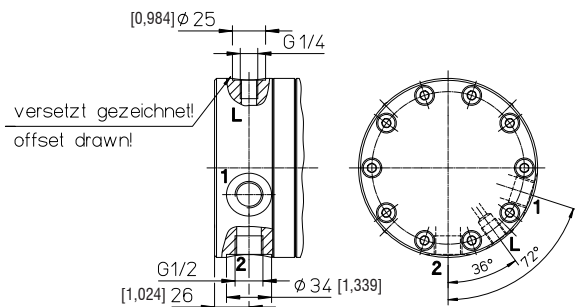
Alternative End Cover B5

Inch measurements in brackets

HFC	Reduce HFC pressure to 70 % Check the bearing service life	Definition to CETOP RP 77 H ISO/DIS 6071
HFD	FPM-/FKM seals are required	

Filtering

Max. permissible degree of contamination of the pressure fluid according to NAS 1638 class 9.
We recommend filters with a minimum retention rate of $\beta_{10} \geq 100$
For a long service life we recommend filtering acc. to NAS 1638 class 8 and filters with a minimum retention rate of $\beta_5 \geq 100$.

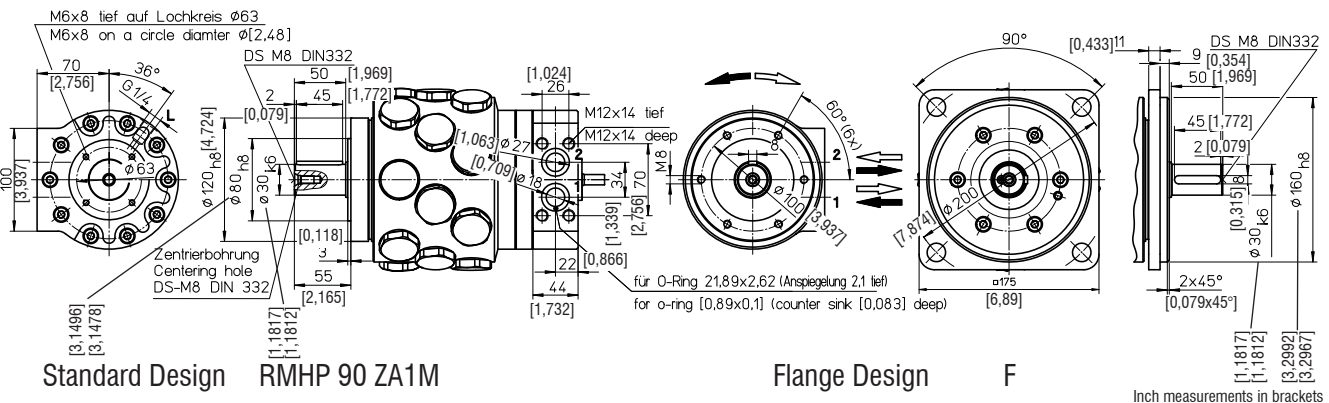


Alternative End Cover A

Inch measurements in brackets

Characteristic values according to VDI 3278

Weight:	[kg]	25,2
Mounting position:	as required	
Direction of rotation, if viewed at the shaft end		
clockwise:	flow from connection 2 to connection 1	
anti-clockwise:	flow from connection 1 to connection 2	
Operating speed range:	[rpm]	1-750
Moment of inertia:	[kgm ²]	0,00034
Continuous power:	[kW]	8,5
Intermittent power:	[kW]	10,0



Standard Design RMHP 90 ZA1M

Flange Design F

Inch measurements in brackets

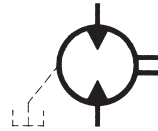
Type number key for radial piston motor RMHP 110

RMHP	Size	Shaft end	End cover	Seal	Instrument shaft ¹⁾	Flange	additional specs.
Radial Piston Motor	110	Keyway Z	Valve face A1 Radial ports A Axial ports B5	NBR FPM V	with M without	S=Ø 80;K=Ø100 S=Ø160;K=Ø200 S=Ø120;K=Ø140 F F3	with out flush connection S99

¹⁾ In Case of B5 flange, instrument shaft is not possible

Changes reserved!

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Pressure medium: HLP 46

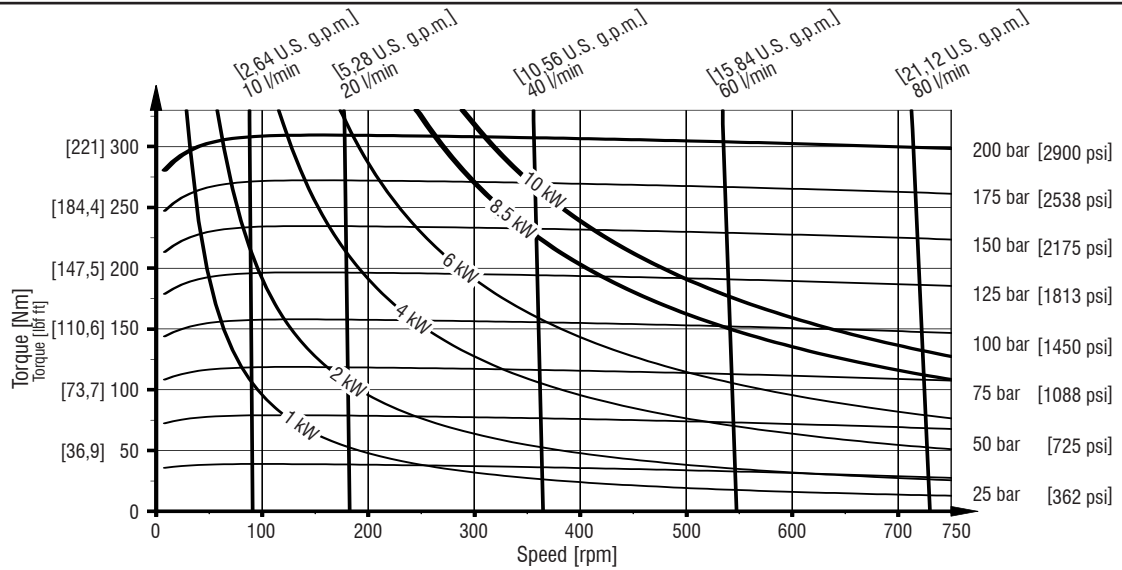
operating temperature: $T = 50^{\circ}\text{C}$

pressure difference: $\Delta p = p_1 - p_2$;

$p_2 = 0$ bar

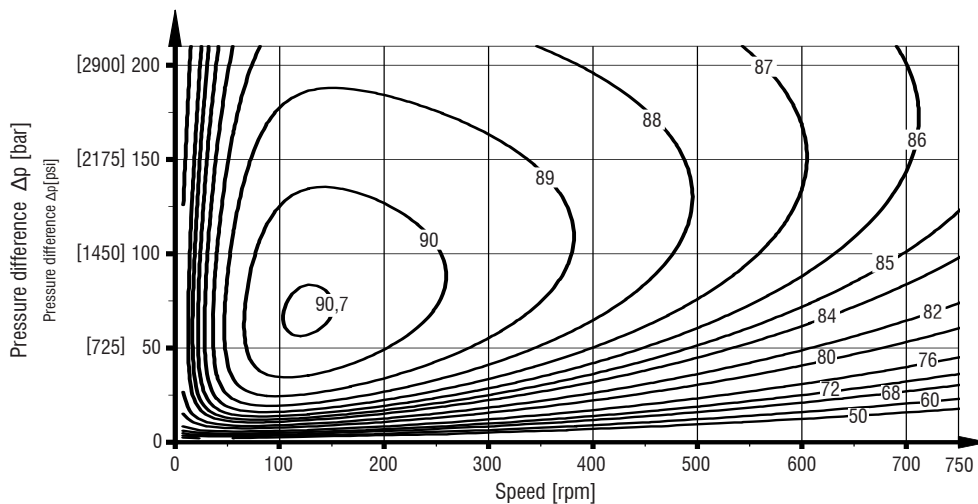
Torque characteristic

Diagram A:



Hydraulic-mechanical efficiency in percentage

Diagram B:



Strength of the shaft

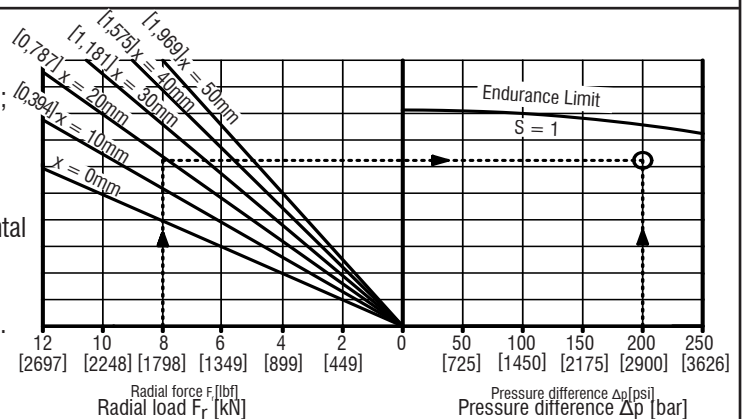
Diagram C:

Example

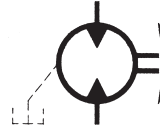
Given: $F_r = 8 \text{ kN}$ [1798 lbf]; $x = 20 \text{ mm}$ [0.787 in]; $\Delta p = 200 \text{ bar}$ [2900 psi]

Required: shaft strength

Draw a vertical line from $F_r = 8 \text{ kN}$ [1798 lbf] to distance $x = 20 \text{ mm}$ [0,787 in] and a straight horizontal line from there. If the intersection of the horizontal with the vertical line of $\Delta p = 200 \text{ bar}$ [2900 psi] is below curve the shaft has sufficient fatigue strength.



Changes reserved!



Pressure medium: HLP 46

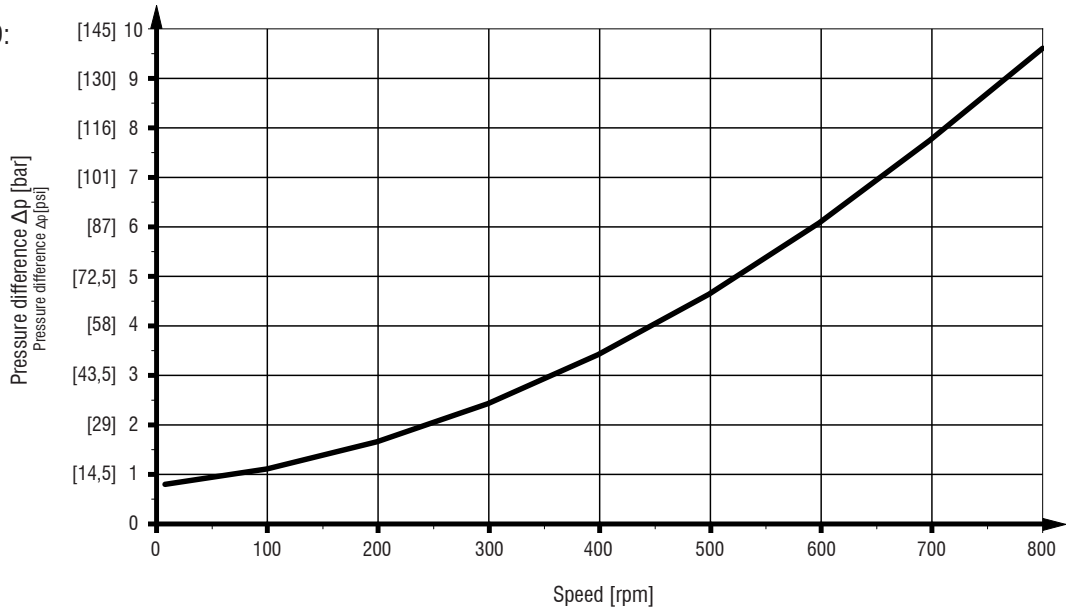
operating temperature: $T = 50^{\circ}\text{C}$

pressure difference: $\Delta p = p_1 - p_2$;

$p_2 = 0 \text{ bar}$

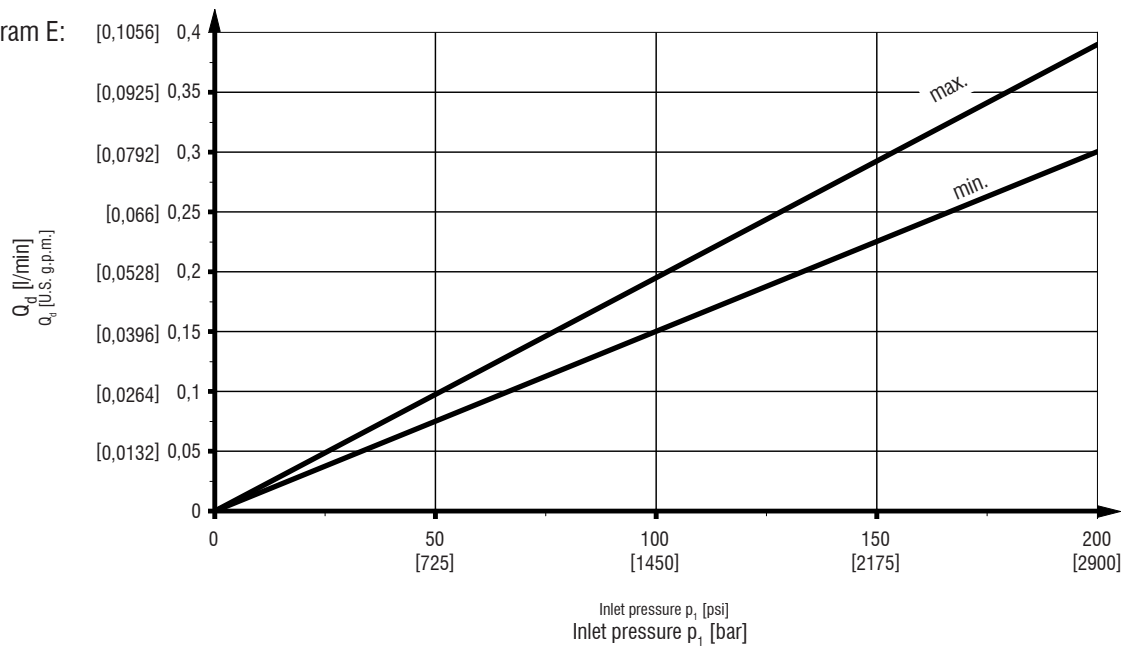
Idle speed

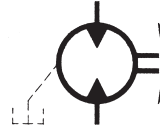
Diagram D:



External leakage through flow

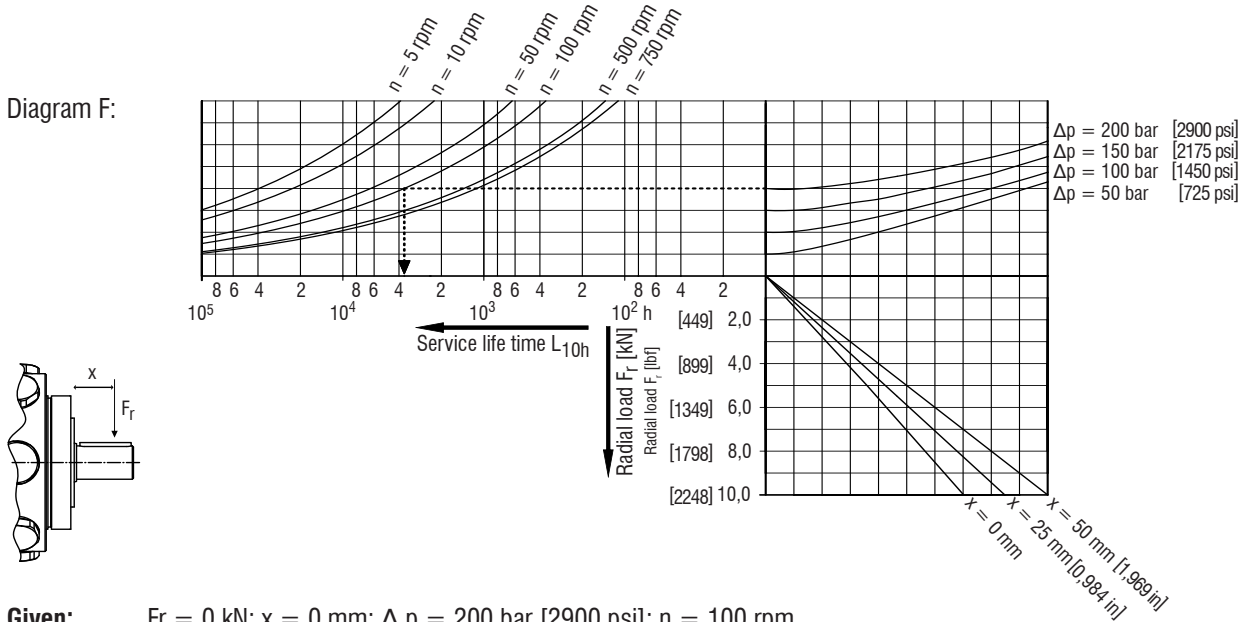
Diagram E:





Service life of the radial bearing loaded with a radial force facing the drive shaft.

Diagram F:



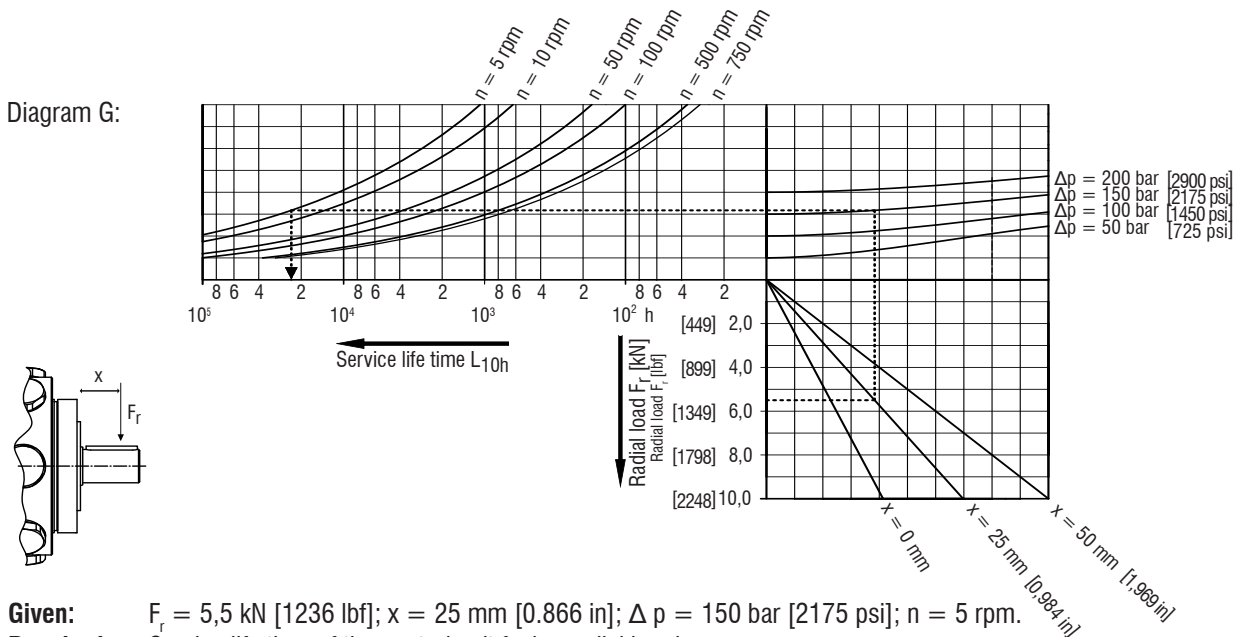
Given: $F_r = 0 \text{ kN}$; $x = 0 \text{ mm}$; $\Delta p = 200 \text{ bar}$ [2900 psi]; $n = 100 \text{ rpm}$.
Required: Service life time of the drive shaft facing radial bearing.

Diagram F:

Form a horizontal line from the $\Delta p = 200 \text{ bar}$ [2900 psi] curve to the $n = 100 \text{ rpm}$ curve. A vertical line down from the intersection shows a service life time value of $L_{10h} = 3665,5 \text{ h}$.

Service life of the radial bearing loaded with a radial force facing the control unit.

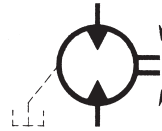
Diagram G:



Given: $F_r = 5,5 \text{ kN}$ [1236 lbf]; $x = 25 \text{ mm}$ [0.866 in]; $\Delta p = 150 \text{ bar}$ [2175 psi]; $n = 5 \text{ rpm}$.
Required: Service life time of the control unit facing radial bearing.

Diagram G:

Form a horizontal line from $F_r = 5,5 \text{ kN}$ [1236 lbf] to $x = 25 \text{ mm}$ [0.866 in]. From the intersection form a vertical line to the pressure curve $\Delta p = 150 \text{ bar}$ [2175 psi]. Afterwards, draw a line from the pressure curve to the speed curve $n = 5 \text{ rpm}$. The intersection dedicates the service life time $L_{10h} = 23351 \text{ h}$.



AEHP 40 ZA1

Hydraulic characteristic values AEHP 40

Geometr. displacement:	[ccm/rev]	43,7
Theor.spec. torque:	[Nm/bar]	0,7
Average spec. torque:	[Nm/bar]	0,63
Peak pressure:*	[bar]	315,0
Max. operating pressure:**	[bar]	250,0
Continuous pressure:	[bar]	210,0
Max. operating torque:	[Nm]	159,0
Continuous torque:	[Nm]	131,5
Drain line pressure:	[bar]	

Hydraulic fluid temperature range:	[K]	243- 363
	[°C]	-30- +90
Viscosity range:	[mm ² /s]	20- 150
	(max. 1000 mm ² /s at start)	

Pressure fluids:
HM and HV, definition to CETOP RP 75 H (mineral oil based fluids).
Mineral oil H-LP in conformity with DIN 51424 part 2.
Bio-degradable fluids available on request.

* Definition according to DIN 24 312. Peak pressure = exceeding the maximum operating pressure for a short time at which the motor remains able to function.
** If the sum of inlet pressure and outlet pressure is higher than the peak pressure, please consult the manufacturer.

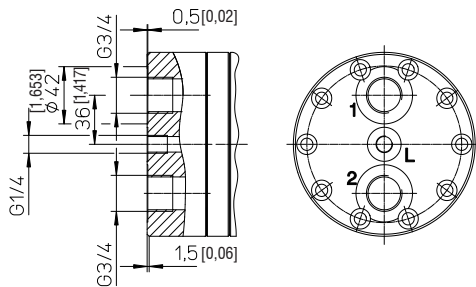
HFC	Reduce HFC pressure to 70 % Check the bearing service life	Definition to CETOP RP 77 H ISO/DIS 6071
HFD	FPM-/FKM seals are required	

Filtering
Max. permissible degree of contamination of the pressure fluid according to NAS 1638 class 9.

We recommend filters with a minimum retention rate of $\beta_{10} \geq 100$
For a long service life we recommend filtering acc. to NAS 1638 class 8 and filters with a minimum retention rate of $\beta_5 \geq 100$.

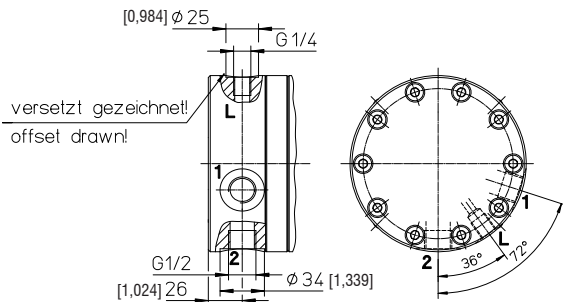
Characteristic values according to VDI 3278

Weight:	[kg]	25,0
Mounting position:	as required	
Direction of rotation, if viewed at the shaft end		
clockwise:	flow from connection 2 to connection 1	
anti-clockwise:	flow from connection 1 to connection 2	
Operating speed range:	[rpm]	1÷2000
Moment of inertia:	[kgm ²]	0,0011
Continuous power:	[kW]	18,0
Intermittent power:	[kW]	21,0



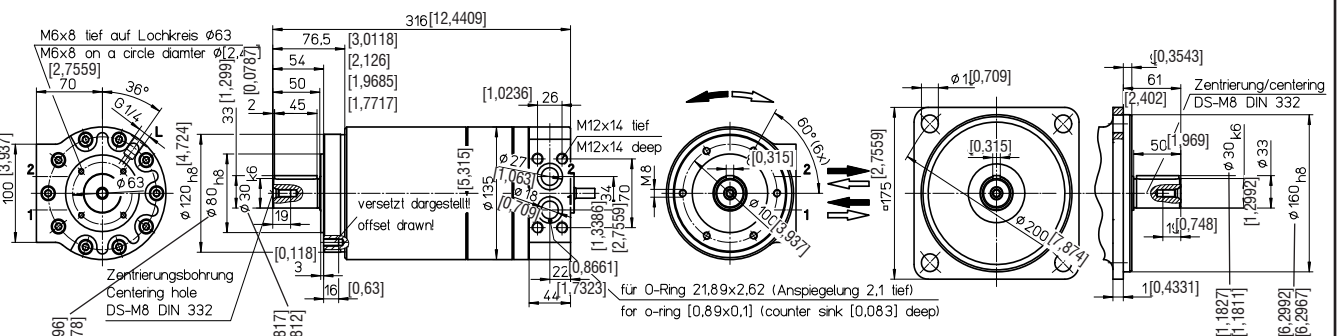
Alternative End Cover B5

Inch measurements in brackets



Alternative End Cover A

Inch measurements in brackets



Standard Design AEHP 40 ZA1M

Flange Design F

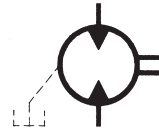
Type number key for axial piston motor AEHP 40

AEHP	Size 40	Shaft end Keyway Z	End cover Valve face A1 Radial ports A Axial ports B5	Seal NBR FPM V	Instrument shaft ¹⁾ with M without	Flange S=Ø 80;K=Ø100 S=Ø160;K=Ø200 F	additional specs. The AEHP is standardized equipped with a flush conection S99
------	------------	-----------------------	--	----------------------	---	--	---

¹⁾ In Case of B5 flange, instrument shaft is not possible

Changes reserved!

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Pressure medium: HLP 46

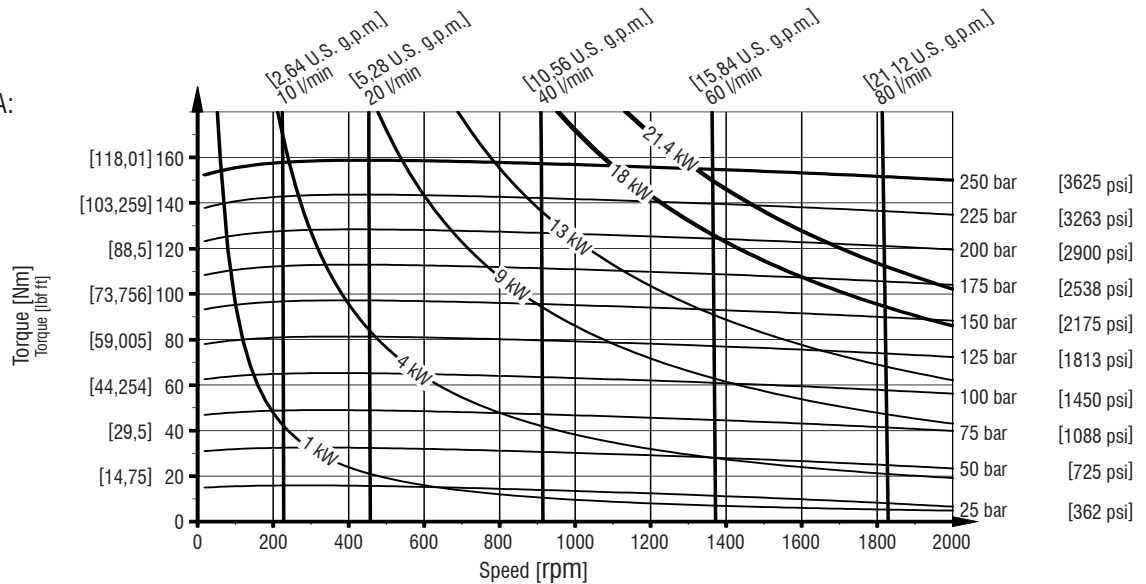
operating temperature: $T = 50^{\circ}\text{C}$

pressure difference: $\Delta p = p_1 - p_2$;

$p_2 = 0$ bar

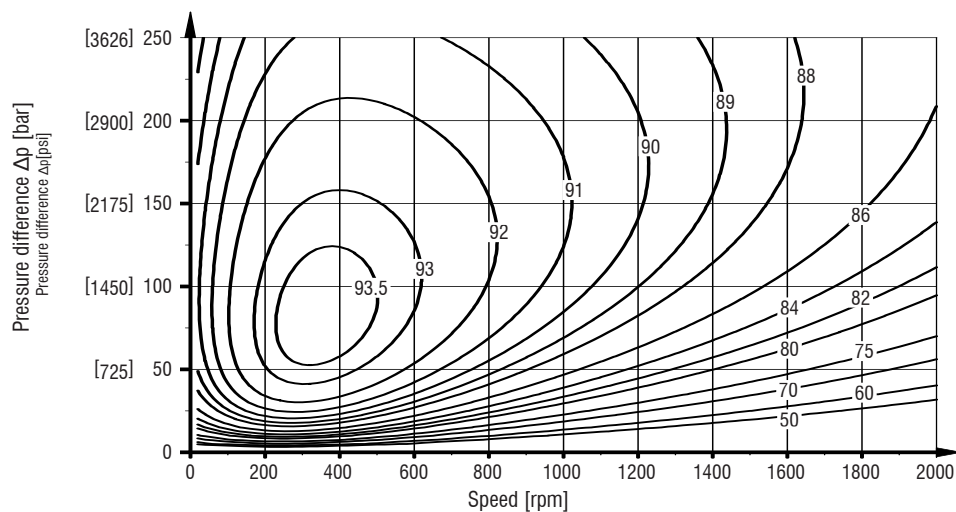
Torque characteristic

Diagram A:



Hydraulic-mechanical efficiency in percentage

Diagram B:



Strength of the shaft

Diagram C:

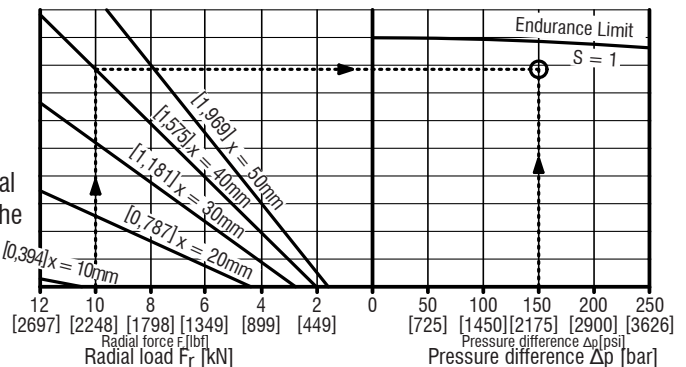
Example

Given: $F_r = 10$ kN [2248 lbf]; $x = 40$ mm;

$\Delta p = 150$ bar [2175 psi]

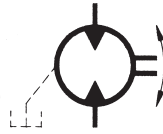
Required: Strength

Draw a vertical line from $F_r = 10$ kN [2248 lbf] to distance $x = 40$ mm [1,5748 in] and a straight horizontal line from there. If the intersection of the horizontal with the vertical line of $\Delta p = 150$ bar [2175 psi] is below curve the shaft has sufficient fatigue strength.



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Pressure medium: HLP 46

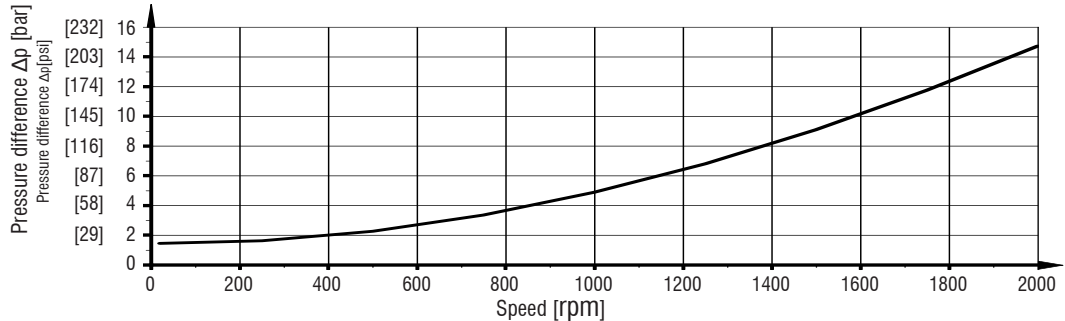
operating temperature: $T = 50^{\circ}\text{C}$

pressure difference: $\Delta p = p_1 - p_2$;

$p_2 = 0$ bar

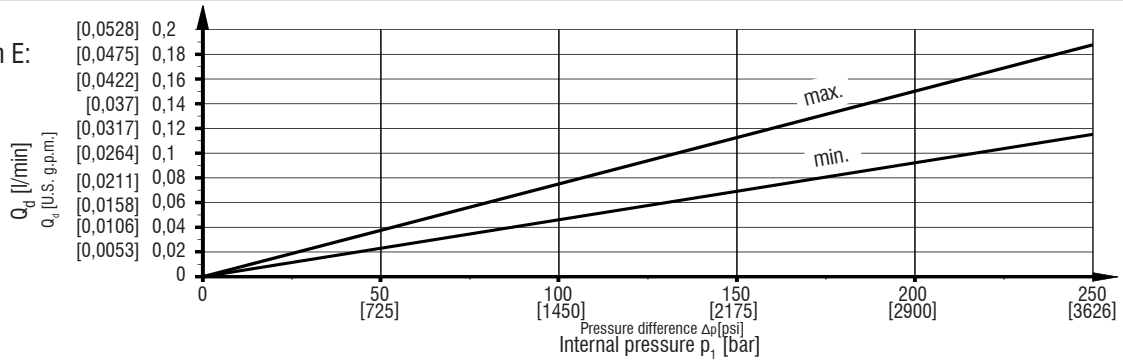
Idle speed

Diagram D:



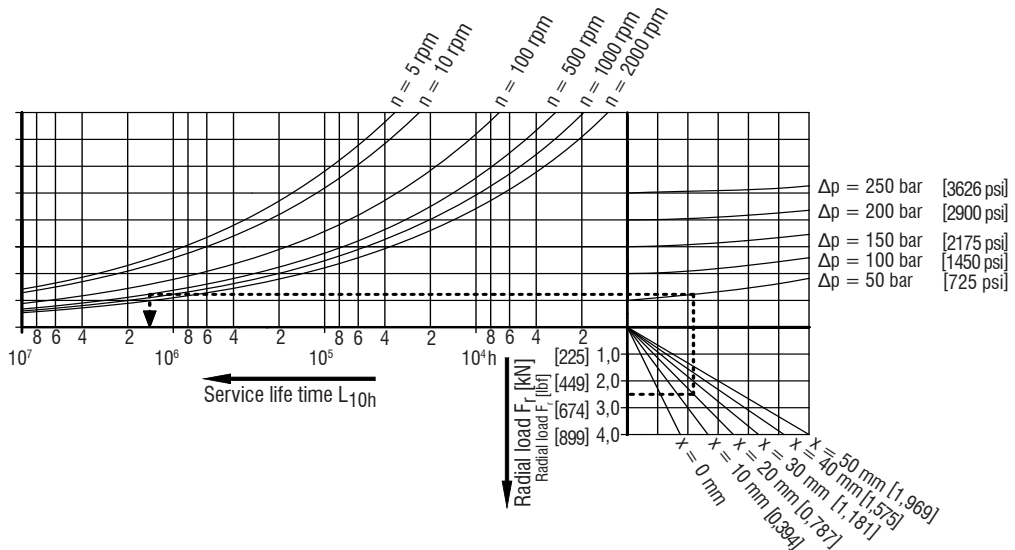
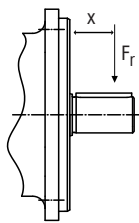
External leakage through flow

Diagram E:



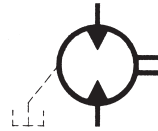
Service life of the radial bearing loaded with a radial force facing the control unit.

Diagram F:



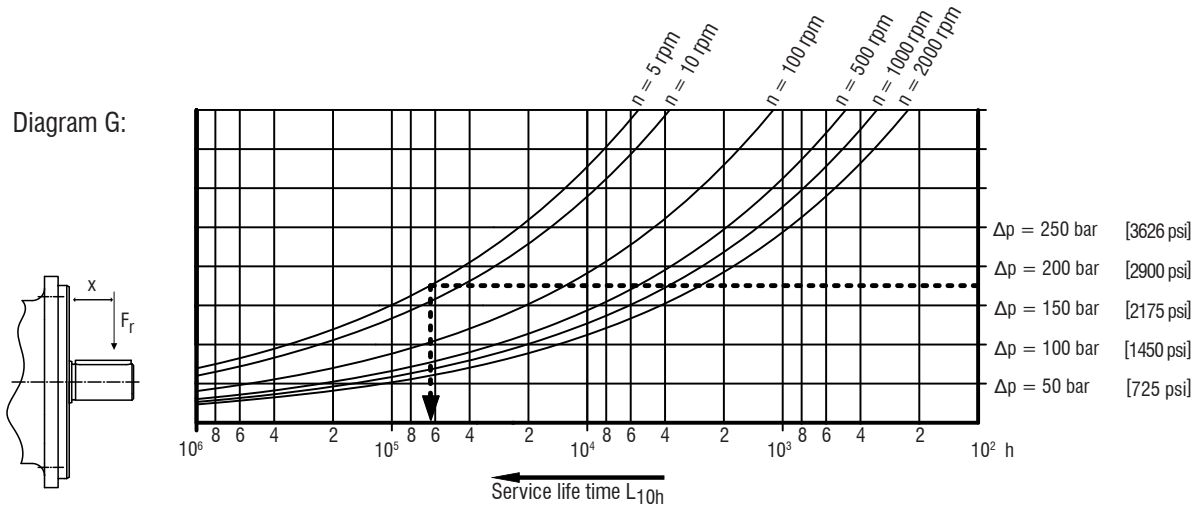
Given: $F_r = 2,5$ kN [562 lbf]; $x = 25$ mm [0.9843 in]; $\Delta p = 50$ bar [2175 psi]; $n = 500$ rpm.
Required: Service life time of the control unit facing radial bearing.

Diagram F:
Form a horizontal line from $F_r = 2,5$ kN [562 lbf] to $x = 20$ mm [0.7874 in]. From the intersection form a vertical line to the pressure curve $\Delta p = 50$ bar [2175 psi]. Afterwards, draw a line from the pressure curve to the speed curve $n = 500$ rpm. The intersection shows the service life time $L_{10h} = 1.686.674$ h.



Service life of the axial bearing facing the output shaft.

Diagram G:



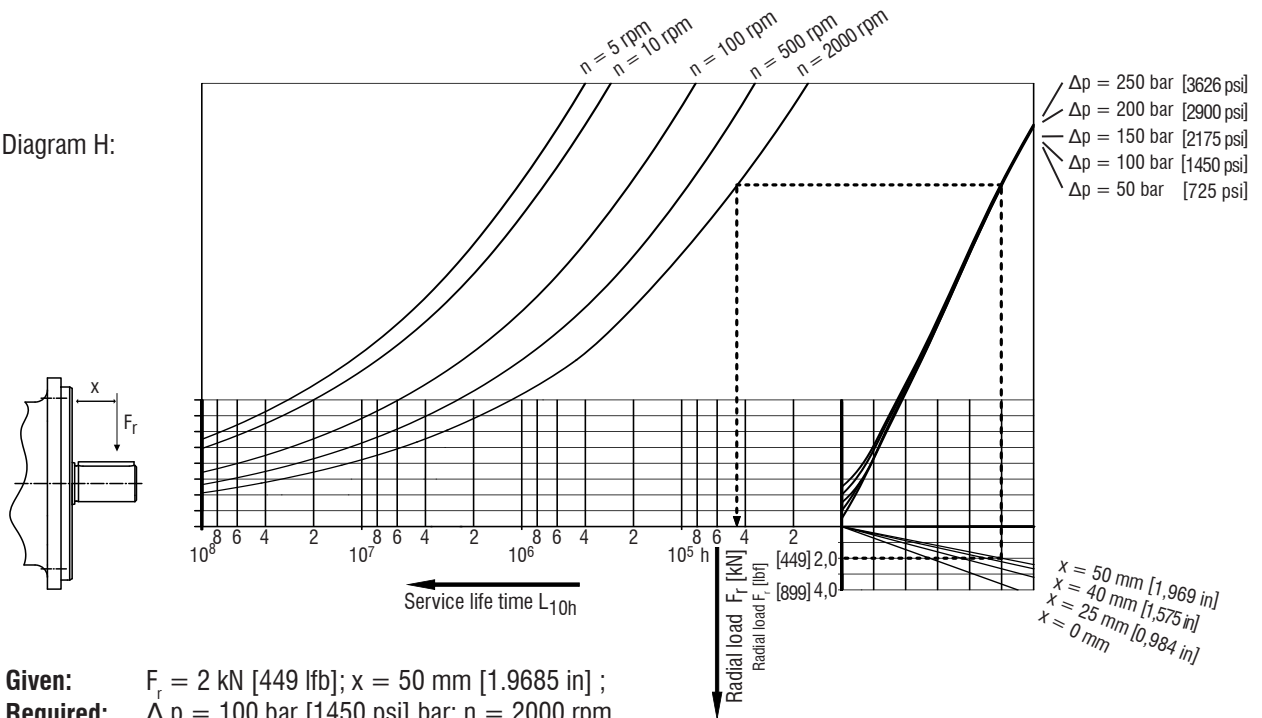
Given: $F_r = 0 \text{ kN}$; $x = 0 \text{ mm}$; $\Delta p = 175 \text{ bar}$ [2538 psi]; $n = 5 \text{ rpm}$.
Required: Service life time of the axial bearing facing the control unit.

Diagram G:

Form a horizontal line from the pressure curve $\Delta p = 175 \text{ bar}$ [2175 psi]. Afterwards, draw a vertical from $n = 5 \text{ rpm}$. The intersection shows the service life time $L_{10h} = 71.068 \text{ h}$.

Service life of the radial bearing loaded with a radial force facing the output shaft.

Diagram H:



Given: $F_r = 2 \text{ kN}$ [449 lbf]; $x = 50 \text{ mm}$ [1.9685 in];
Required: $\Delta p = 100 \text{ bar}$ [1450 psi] bar; $n = 2000 \text{ rpm}$.
Service life time of the control unit facing radial bearing.

Diagram H:

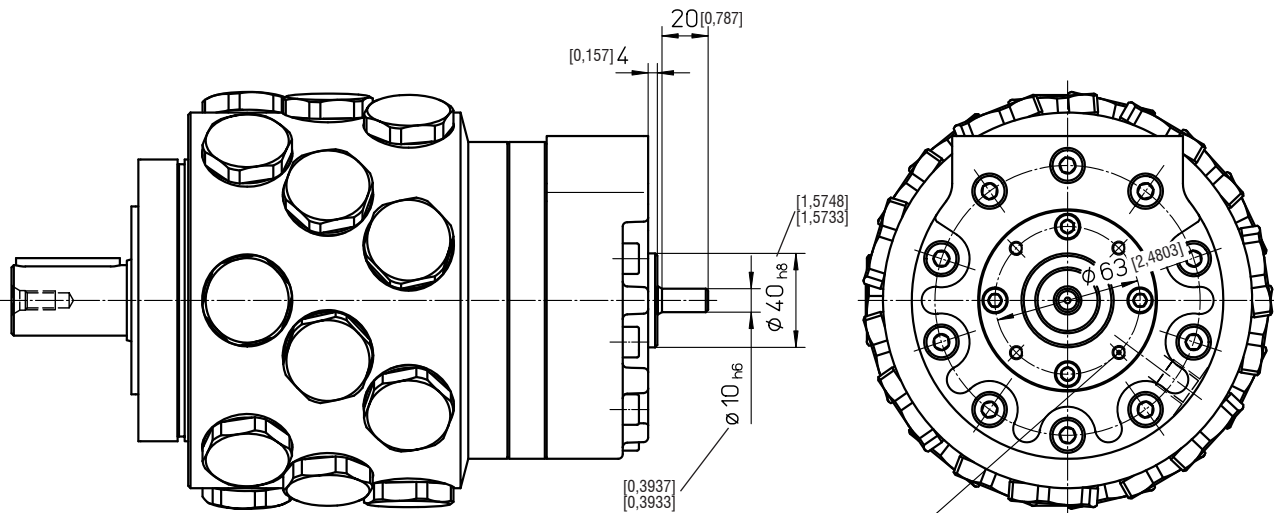
Form a horizontal line from $F_r = 2 \text{ kN}$ [449 lbf] to $x = 50 \text{ mm}$ [1.9685 in]. From the intersection form a vertical line to the pressure curve $\Delta p = 100 \text{ bar}$. Afterwards, draw a line from the pressure curve to the speed curve $n = 2000 \text{ rpm}$. The intersection shows the service life time $L_{10h} = 45.477 \text{ h}$.

Changes reserved!

Cylindrical measuring shaft: M

Radial- and axial piston motors of the series RMHP 90, RMHP 110 and AEHP 40 with the additional denotation "M" are coupled to a cylindrical measuring shaft to determine the speed of the engine. The cylindrical measuring shaft is fixed to the crankshaft and is able to assign a torque of about 5 Nm [3,688 lbf ft]. If a higher torque is required, please request separately. Informations about accessories like speed indicators, dynamos, impuls generators and power frequency generators please request also separately.

RMHP 90 ZA1M:



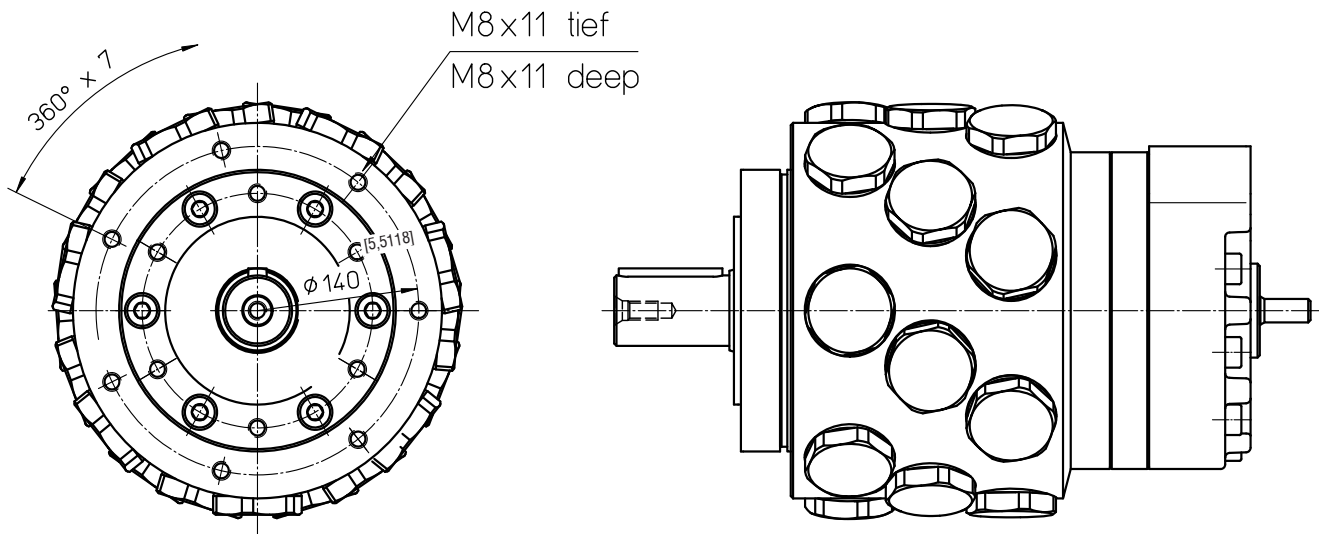
4 Gewindebohrungen M6x8mm tief
4 screw holes M6x8mm deep

Inch measurements in brackets

Flange connection: F3 (just RMHP)

Seven additional mounting boreholes M8 x 11 deep on a pitch circle \varnothing 140 [5,5118].

RMHP 90 ZA1MF3:



Inch measurements in brackets

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You know your product, we know our high-precision motors! Give us your conditions, we will calculate all important data for a suitable drive.

1. **Company*** _____ **For attention of*** _____
 Street / P.O.Box _____ Department _____
 Postal code / City _____ **Phone No*** _____
 Country _____ **E-Mail*** _____

2. **Operating data:** secondary drive

2.1 Machine type: _____ project: _____
 2.2 Machine operating factor / gearboxes $k =$ _____
 2.3 Installation position: horizontal vertical
 drive shaft upwards drive shaft downwards
 2.4 Forces on drive shaft: pressure tension
 radial: _____ N axial: _____ N
 2.5 Nominal torque $T_N =$ _____ Nm speed $n =$ _____ min⁻¹ time = _____ min
 2.6 **Continuous torque*** $T_{cont}^* =$ _____ Nm **speed $n^* =$ _____ min⁻¹ time = _____ min**
 2.7 Maximum torque $T_{max} =$ _____ Nm speed $n =$ _____ min⁻¹ time = _____ min
 2.8 Minimum torque $T_{min} =$ _____ Nm speed $n =$ _____ min⁻¹ time = _____ min
 2.9 Maximum speed $n_{max} =$ _____ min⁻¹ time $t =$ _____ min
 2.10 Minimum speed $n_{min} =$ _____ min⁻¹ time $t =$ _____ min
 2.11 Information about working cycle: _____
 2.12 Secondary drive with valve assembly on the motor
 2.13 Control drive with proportional- / servo valve
 2.14 Maximum power: $P_{max} =$ _____ kW **continuous power*: $P_{dauer}^* =$ _____ kW**
 2.15 one-shift-operation two-shift-operation three-shift-operation
 2.16 Desired bearing life: $L_{h10} =$ _____ hours
 2.17 Remarks: _____

3. **Operating data:** primary drive

Hydraulic fluid: _____
 operating temperature: $\Theta =$ _____ °C
 Delivery volume of pump $Q_p =$ _____ l/min
 opened circuit closed circuit
 Feeding pressure $p_F =$ _____ bar
 System pressure $p_{sys} =$ _____ bar
 Desired operating pressure at T_N $p_N \sim$ _____ bar

*** Requested fields, which are necessary for the first design.**
(The more informations we get about the technical conditions and the application area, the more specific will be our consulting and design for you.)



DÜSTERLOH has been developing fluid technology products for more than 100 years.

The drives, controls and hydraulic power units from Hattingen are appreciated throughout the world for their complete reliability; including under extreme conditions. The owner-managed company's own development and construction department and the wide range of products cater for distinctive flexibility and customer-orientation.

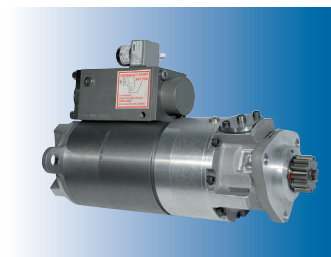
Products

- Hydraulic radial piston motors
- Hydraulic axial piston motors
- Pneumatic motors
- Pneumatic starters
- Hydraulic and pneumatic controls
- Hydraulic power units

Designing controls and hydraulic power units specific to the customer is our company's major strength. Vast product diversity is also available for standardized products.

Industrial areas of application

- Machine tools
- Smelting and rolling mill equipment
- Foundry machines
- Testing machines
- Shipbuilding (diesel engines)
- Offshore technology
- Printing and paper technology
- Vehicle construction
- Manipulators
- Environmental technology
- Mining equipment
- Materials handling equipment



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